

# 北京亿利泰达科技有限公司

Beijing Eletechnic Ltd.

## Φ37-20211-48 Brushless DC Motor Product Datasheet

## Ф37-20211-48 BLDC Overview

- Three Phase, Six Step, Full Wave, Y-Circuit
- Sintered Nd-Fe-B Permanent Magnet Rotor
- Hall Sensor / Sensorless
- Step (Cogging)
- Slot

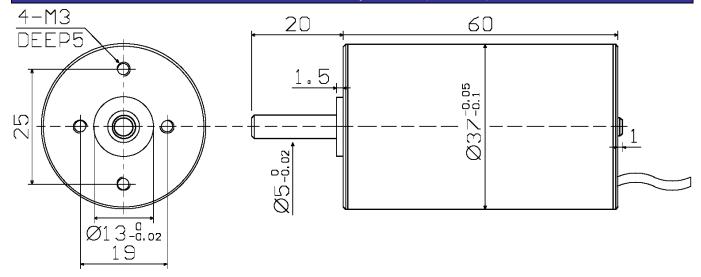


| Parameters                    | Φ37-20211-48 BLDC Absolute Maximum Ratings |            |
|-------------------------------|--|------------|
| Rotor/Bearing Broken Speed    | 25000                                      | rpm        |
| Winding and Rotor Temperature | -20 to +130                                | $^{\circ}$ |
| Ambient Temperature           | -20 to +85                                 | $^{\circ}$ |

Notice: The Absolute Maximum Ratings are those values beyond which the safety of the device cannot be guaranteed

| Parameters                           | Ф37-20211-48 BLI | Unit                          |       |  |
|--------------------------------------|------------------|-------------------------------|-------|--|
| Resistance (Including 0.5m Line)     |                  | Ohm                           |       |  |
| Speed-Torque Gradient                |                  | rpm/Nm                        |       |  |
| Torque Constant                      |                  | Nm/A                          |       |  |
| Speed Constant                       |                  | rpm/V                         |       |  |
| Back-EMF Constant                    |                  | mV/rpm                        |       |  |
| Rotor Magnetic Poles                 |                  | 4                             | Poles |  |
| Ball Bearing No Load Continuous Life | 10000            | (Please order if have special | Hours |  |
| (At Nominal Voltage)                 | 10000            | requirement)                  | Hours |  |
| Weight (Including 0.5m Line)         | Approximate      | 250                           | g     |  |

### Φ37-20211-48 BLDC Physical Size (Unit: mm)

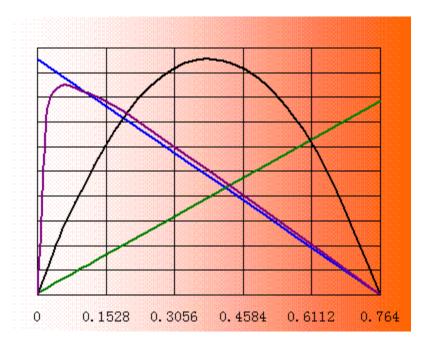




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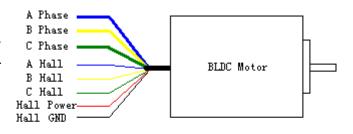
| Parameters                          | Φ37-20211-48 BLDC Performance Characteristics (20℃)  |       |       |       |       | Unit |
|-------------------------------------|--|-------|-------|-------|-------|------|
| Nominal Voltage                     | 48   |       |       |       |       |      |
| Maximum Output Power                | 383  |       |       |       |       |      |
| (See Curves Below)                  | No Load Point Some Loaded Points Performance   |       |       |       |       |      |
| Output Torque                       | 0  | 0.06  | 0.08  | 0.1   | 0.12  | Nm   |
| Output Speed                        | 19120  | 17620 | 17120 | 16620 | 16120 | rpm  |
| Input Current                       | 0.27   | 2.72  | 3.53  | 4.35  | 5.16  | A    |
| Output Power                        | 0  | 111   | 143   | 174   | 203   | W    |
| Efficiency                          | 0  | 85    | 85    | 83    | 82    | %    |
| External Forced Ventilation Cooling | If the shell temperature of the motor is higher than 85°C, more effective cooling equipments must be installed. Otherwise the motor may be damaged by hotness. |       |       |       |       |      |



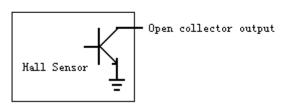


### Ф37-20211-48 BLDC Connection Diagram and Hall Output Waveforms

- Connection: Blue thick--A phase, Yellow thick--B phase, Green thick--C phase, Blue thin--A hall, Yellow thin--B hall, Green thin--C hall, Red thin--Hall power supply, Black thin--Hall GND
- Hall Supply Voltage: 4.5 to 16VDC Regulated Supply
- Hall Power Supply Current: Less than 30mA
- Hall Output: Open collector. Require external pull-up resistors for proper logical operation. Maximum output voltage is 16V
- Electrical Hall Sensor Phasing: 120°
- Line Length: 0.5m, (Please order if have special requirement)



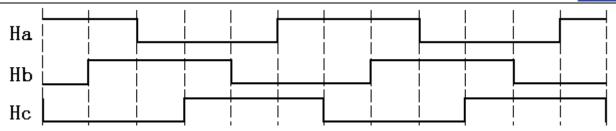
Torque(Nm)





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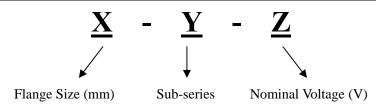
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Hall Sensor Output Commutation Waveforms

Notice: The A, B, C three windings and Ha, Hb, Hc three hall sensors must be connected correctly, otherwise the controller and motor may be damaged.

### **Eletechnic BLDC Motor Product Code Regulation**



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#### How to reach us:

Address:

Chang Ping Qu, Er Bo Zi Gong Ye Yuan, Bei Qu Zhong Lu No.7

Beijing, 102208

P. R. China

Tel: 0086-10-68422061 Fax: 0086-10-68422061

EMAIL: <u>SALES@ELETECHNIC.COM</u>
<a href="https://www.eletechnic.com">HTTP://www.eletechnic.com</a>
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